

## IMPROVED COMPUTER-AIDED SYNTHESIS TOOLS FOR THE DESIGN OF MATCHING NETWORKS FOR WIDEBAND MICROWAVE AMPLIFIERS

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**ABSTRACT**--Network synthesis is a powerful design tool when applied to the design of matching networks for wideband microwave amplifiers. Significant design improvements have been made in the computer-aided synthesis process which provides a powerful, efficient and friendly tool for the microwave amplifier designer. Design methodologies are given, computer automation methods outlined and a complete amplifier design example is included.

### A. INTRODUCTION

Network synthesis has long been a workhorse tool for the design of low-frequency and microwave filters. In recent years, it has begun to be applied to the problem of wideband matching networks for microwave amplifiers<sup>1-2</sup> via extensions of classical synthesis techniques. This paper describes significant improvements in the synthesis of matching networks for wideband amplifiers and in the automation thereof. The key improvements are:

1. A simplified and automated method of modeling device impedances.
2. A methodology for selecting topologies that meet parasitic inclusion and impedance transformation requirements which is efficiently automated.
3. An automated method for adjusting the gain-bandwidth and selecting reflection coefficient zeros consistent with parasites to be included.

These improvements provide a powerful, friendly and useful tool for the microwave amplifier designer.

In Section B, the synthesis design process as applied to wideband matching networks is outlined with attention called to the steps which have been significantly improved via the techniques described in this paper.

Sections C, D, and E describe in detail the areas of improved design methods in the matching network synthesis process.

Section F describes a complete microwave amplifier design using the design techniques of this paper.

Section G summarizes the results and benefits possible using the design methodologies of this paper.

### B. STEPS IN THE MATCHING NETWORK SYNTHESIS PROCESS

The steps in matching network synthesis are outlined in Figure 1 and listed here. Steps shown with an (\*) indicate areas in which significant improvements have been made via the techniques described in the following sections.

- \*1. Model the input and output impedance of the active devices to be used in the microwave amplifier.
2. Select a topology consistent with device parasitics.
- \*3. Adjust the gain-bandwidth to insure inclusion of parasitics.
- \*4. Select the reflection coefficient zeros consistent with inclusion of parasitics.
5. Transform impedances to desired levels.
6. Transform the lumped design to a transmission line realization.
7. Analyze the resultant design by itself and/or as part of the complete amplifier design.
8. Optimize the amplifier design (if needed).

### C. A SIMPLIFIED AND AUTOMATED METHOD OF MODELING DEVICE IMPEDANCES

The input and output impedances of active devices have generally been modeled by curve-fitting, optimization or Smith Chart manipulation. A simpler algebraic method which provides very satisfactory accuracy and greatly improved speed

and convenience is achieved by using the simple impedance models shown in Figure 2. The modeled element values are then obtained by applying the following constraints to the three different types of circuits:

Circuit Type	Constraint at $f_u$ (upper passband edge)	Constraint at $f_l$ (lower passband edge)
- Two Element Networks	- Exact agreement with measured impedance; both real and imaginary parts	- None
- Three Element Series -Series or Shunt- Shunt type	- Exact agreement of both real and imaginary parts	- Agreement of imaginary parts
- Three Element Series Shunt Type	- Exact agreement of both real and imaginary parts	- Agreement of real parts

Then the behavior of the model at  $f_l$  is compared to the device impedance from measured S-parameters. From the networks which yield a realizable network, the impedance model which has the greatest accuracy at  $f_l$  is chosen. The degree of accuracy of the model at  $f_l$  is obtained by simply computing the resultant model behavior at  $f_l$ , comparing to the actual Z behavior at  $f_l$  and computing the potential matching error due to modelling inaccuracy.

This method yields very accurate results with quite simple models. An application example is given with the amplifier design of Section F.

An example of the resulting equations from applying the outlined constraints is as follows:

$$\begin{aligned}
 & \text{Measured Impedance} \\
 & Z = \frac{(1 + S_{11})}{(1 - S_{11})} Z_0 \quad i = 1 \text{ for Input} \\
 & \quad \quad \quad \quad \quad i = 2 \text{ for Output} \\
 & Z = R_u + jX_u = \frac{1}{G_u + jB_u} \quad \epsilon \epsilon = \epsilon_u \\
 & Z = R_l + jX_l = \frac{1}{G_l + jB_l} \quad \epsilon \epsilon = \epsilon_l \\
 \\
 & \text{Resulting Equations} \\
 & R = \frac{(1/G_u - (\epsilon_u/\epsilon_l)^2/G_l)}{1 - (\epsilon_u/\epsilon_l)^2} \quad (1) \\
 & L = \frac{\sqrt{R/G_u - R^2}}{2\pi\epsilon_u} \quad (2) \\
 & C = \frac{R_u + (2\pi\epsilon_u L)/(R^2 + (2\pi\epsilon_u L)^2)}{2\pi\epsilon_u} \quad (3)
 \end{aligned}$$



#### D. SIMPLIFIED AND AUTOMATED SELECTION OF TOPOLOGIES FOR MATCHING NETWORK SYNTHESIS

Topology selection has been a stumbling block in matching network synthesis for the following reasons:

- Many topologies are available which provide a valid result even after parasitic constraints are applied.

- Topologies vary in their ability to provide impedance transformations and there is no known way to predict the impedance-transforming capability of a network before it is synthesized.

Given then that many topologies are available and that there are no known a-priori methods for selecting a good topology, the following options were considered in an effort to more efficiently select topologies:

METHOD 1) Allow (require) the designer to try various topologies and manually select the one which meets his parasitic inclusion and impedance transformation requirements: This has been the traditional approach but is extremely inefficient on the time (and patience) of the microwave designer.

METHOD 2) Have the computer search through all possible topologies and select out those topologies which meet parasitic inclusion and impedance transformation requirements. This is much more efficient than 1) since the elimination of invalid topologies is done by the computer. However, the topology search and eliminate process must be done each and every time the designer performs a synthesis and it still leaves the user to select among the valid topologies that are left.

METHOD 3) Do an a-priori study to determine good default topologies for specific combinations of parasitics that need to be included on each side of the network. A good topology would accommodate the existent parasitics and provide a wide range of impedance transformation capability. This method provides for the simplest selection of a default topology for the user and would execute in the minimum possible time.

METHOD 3) was selected as the best tradeoff for synthesis of matching networks. Therefore, a study was made to determine which topologies provided a wide range of impedance transformation for a given set of parasitics at each end of the matching network. Several general conclusions were drawn from this study:

1. The impedance transforming capability of a matching network is most strongly dependent upon the topology itself and much less strongly dependant upon the frequency response specification. This discovery makes METHOD 3) very workable since default topologies can be selected based upon the requisite parasitic in-

clusion requirements without regard to the specific frequency response specification.

2. Sufficient flexibility is obtained for matching network topologies without requiring networks any higher than six reactive elements. In fact, fourth order networks are often quite satisfactory in obtaining the requisite bandwidth, parasitic inclusion capability, and impedance transformation. For automation simplicity, all default topologies were chosen to be sixth order matching networks.

An example default topology is given here:

Parasitic Inclusion		Good Default Topology						Approximate Impedance Transforming Range	
# Input	# Output	CP	LP	LS	CP	CS	LS	Minimum	Maximum
CP	LS							1 : 0.054	1 : 5.4

#### E. IMPROVED AND AUTOMATED METHODS OF ADJUSTING THE GAIN-BANDWIDTH AND SELECTING REFLECTION COEFFICIENT ZEROS TO ASSURE INCLUSION OF PARASITIC ELEMENTS

The gain-bandwidth of a synthesis has to be constrained and the reflection coefficients have to be selected (either left half plane or right half plane) properly in order to assure that existent parasitics can be included into synthesized networks. This can be a tedious manual process to adjust the gain, try all combinations of reflection zeros....especially for a microwave designer unfamiliar with synthesis theory.

The approach taken here is to automate the gain-bandwidth adjustment and reflection zero process in the following way:

1. From a given frequency response specification (set by the user), automatically adjust the gain (if and only if necessary) to assure parasitic inclusion and save all solutions that meet the parasitic inclusion requirements. This provides a set of several valid solutions that can be quickly stepped through and selected by the user.
2. The method of gain adjustment is a binary search on the gain parameter whereby:
  - a) A maximum allowable gain is first tested to see if it meets the parasitic requirements (e.g. 1 dB).

- Then half maximum is tested.
- Depending on the results of a) and b), either 1/4 maximum or 3/4 maximum is tested.
- The process continues until the difference between successive successful tests is sufficiently small (e.g. 0.1 dB).

This method is very efficient because the binary search algorithm converges quite rapidly and because the testing for parasitic inclusion can be obtained with straight-forward calculations.

3. The designer is not bothered with the inner workings of the synthesis computations. Rather, the designer specifies requirements such as frequency response, parasitics to be included, source and terminating resistance and is then presented alternative solutions which can be quickly scanned for selection.

#### F. COMPLETE AMPLIFIER DESIGN USING THE TECHNIQUES OF THIS PAPER

AMPLIFIER SPECIFICATIONS : 15 db  $\pm$  2 dB over 6-12 GHz

TRANSISTOR : The (chip) Hp GaAs FET whose parameters are listed in Figure 3.

TRANSISTOR MODELLING : The transistor is shown modelled in Figure 4 using a computer-aided implementation of the techniques of this paper.

MATCHING NETWORK SPECIFICATIONS :

	Gain Slope	Ripple	Parameters To Be Included
Input	6 dB/Oct	.4 dB	FET I/P
Interstage	6 dB/Oct	.4 dB	FET O/P FET I/P
Output	0	.04 dB	FET O/P

The computer-aided design of these networks is shown in Figure 5.

#### ANALYSIS OF COMPLETE AMPLIFIER

Figure 6 and 7 show the analysis of the complete amplifier response. This response is exactly as designed without optimization. Deviations from ideal expectations exist due to the fact that the transistors are not unilateral ( $S_{12} \neq 0$ ) and due to the fact that the transmission-line realization is not an exact representation of the lumped design. Overall, the results are a very good first-cut design and could be improved further through optimization.

#### G. SUMMARY

Simplified and improved synthesis techniques coupled with automation of the same provides a powerful and useable tool in the design of wideband matching networks for microwave amplifiers.

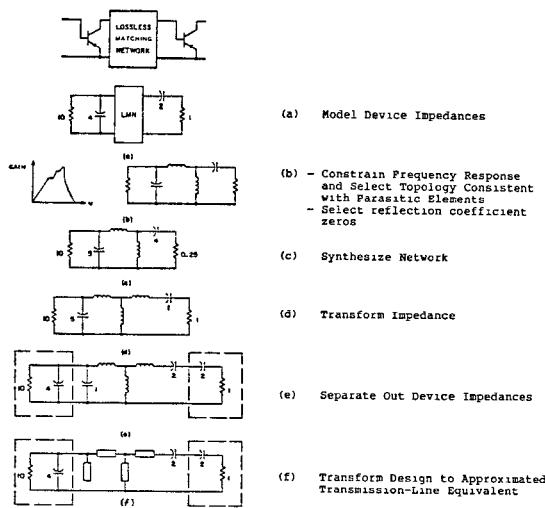


Figure 1. Outline of the Process of Synthesis of Matching Networks for Microwave Amplifiers.

Figure 5. Synthesis of Matching Networks.

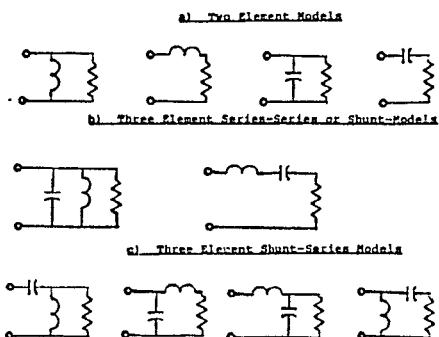


Figure 2. Simple Impedance Models for Modelling Active Device Impedances

Chap. 6. Social and Economic

FREQ-GHZ	MAGS1111	ANGS1111	DECs1111	MAGS1121	ANGS1121	DECs1121	MAGS1211	ANGS1211	DECs1211	MAGS1221	ANGS1221	DECs1221
	FET											
6.00000*	0.745	-97.000	6.825	100.000	0.069	39.000	0.486	-48.000	5.000	0.486	-48.000	5.000
7.00000*	0.741	-107.200	7.224	100.000	0.069	35.000	0.482	-35.000	7.000	0.482	-35.000	7.000
8.00000*	0.713	-118.000	6.884	88.000	0.071	35.000	0.482	-35.000	8.000	0.482	-35.000	8.000
9.00000*	0.708	-122.500	5.872	82.000	0.070	31.000	0.498	-25.000	9.000	0.498	-25.000	9.000
10.00000*	0.696	-127.000	4.726	75.000	0.067	30.000	0.515	-20.000	10.000	0.515	-20.000	10.000
11.00000*	0.681	-129.200	3.750	68.000	0.067	21.500	0.545	-10.000	11.000	0.545	-10.000	11.000
12.00000*	0.678	-122.000	3.098	62.000	0.067	21.500	0.545	-10.000	12.000	0.545	-10.000	12.000

Figure 3. S-parameters of HR GaAs SOT used in Analysis 3.

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SPANNER DATA USED FOR MODEL 1
#(GHz) B11ANG B11ANG B21ANG B22ANG B23ANG
 4.000  0.769 -97.000  27.71  0.486 -148.000
12.000  0.670 -132.000  1.427  0.564 -71.000

ELEMENT VALUES ARE IN Dm pF nH

BEST 2-ELEMENT MODEL FOR S 1 1
CS R 11.4134
0.4231
FIT IS EXACT AT FLOWER - . . . . . ERROR AT Flower = 0.413 %
APPROXIMATE WORST CASE ERROR IN dB = 0.027 dB

BEST 2-ELEMENT MODEL FOR S 2 2
CP R 123.3758
1679
FIT IS EXACT AT FLOWER - . . . . . ERROR AT Flower = 18.413 %
APPROXIMATE WORST CASE ERROR IN dB = 0.734 dB

AVAILABLE GAIN AT Flower = 13.710 dB
AVAILABLE GAIN AT Fupper = 7.422 dB
B11 ROLLOFF = 6.452 dB
B21 ROLLOFF = 6.452 dB
SELECT A SOFTWARE COMMAND ? 6.452 dB/GHz

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Figure 4. PET Gain and Impedance Modelling.

## 2 STAGE GaAs FET AMPLIFIER

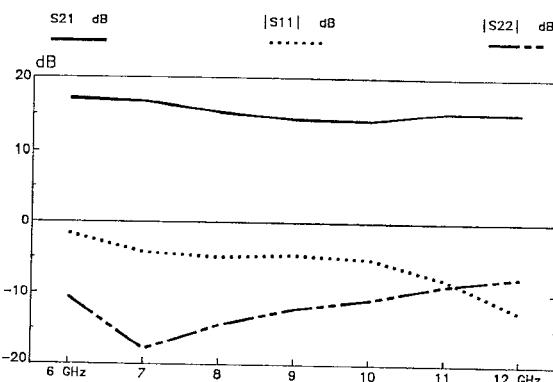


Figure 7. Complete Amplifier Analysis